# Algorithms Transcending the SAT-Symmetry Interface 

Markus Anders Mate Soos Pascal Schweitzer

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## Boolean Satisfiability

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- a disjunction $C \in F$ is called a clause
- an element $I \in C$ is called a literal


## Symmetry Breaking



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- very effective on some instance types (combinatorics, logistics, ...)
- overhead is an issue


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$$
\begin{aligned}
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- symmetries of graph are symmetries of formula (and vice versa)

By the way... what are symmetries again? (CNF)

- bijection of literals $\varphi: \operatorname{Lit}(F) \rightarrow \operatorname{Lit}(F)$ with $\varphi(F)=F$

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\varphi=\left(x_{1} x_{2}\right)\left(\overline{x_{1} x_{2}}\right)\left(y_{1} y_{2}\right)\left(\overline{y_{1} y_{2}}\right)
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$\varphi(F)=$
$\left\{\varphi\left(x_{1}\right) \vee \varphi\left(\overline{y_{1}}\right), \varphi\left(x_{2}\right) \vee \varphi\left(\overline{y_{2}}\right), \varphi\left(x_{3}\right) \vee \varphi\left(\overline{y_{3}}\right), \varphi\left(x_{1}\right) \vee \varphi\left(x_{2}\right) \vee \varphi\left(x_{3}\right) \vee \varphi\left(z_{1}\right) \vee \varphi\left(z_{2}\right)\right\}=$ $\left\{\left(x_{2} \vee \overline{y_{2}}\right),\left(x_{1} \vee \overline{y_{1}}\right),\left(x_{3} \vee \overline{y_{3}}\right),\left(x_{2} \vee x_{1} \vee x_{3} \vee z_{1} \vee z_{2}\right)\right\}=$ $\left\{\left(x_{1} \vee \overline{y_{1}}\right),\left(x_{2} \vee \overline{y_{2}}\right),\left(x_{3} \vee \overline{y_{3}}\right),\left(x_{1} \vee x_{2} \vee x_{3} \vee z_{1} \vee z_{2}\right)\right\}=$
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By the way... what are symmetries again? (Graphs)

- bijection of vertices $\varphi: V \rightarrow V$ with $\varphi(G)=(\varphi(V), \varphi(E))=G$



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- state-of-the-art tools are nauty, saucy, bliss, Traces, dejavu


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automorphisms.org


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## Symmetry Breaking: Refined Picture



## Symmetry Breaking: Refined Picture II



## Symmetry Breaking Sub-Tasks

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row interchangeability
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- structural analysis of permutation group


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Relies on "transpositions":

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disjoint decomposition
recent [Chang, Jefferson, '20]

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- assume production of random elements...
- doesn't make use of graphs or SAT formulas (obviously!)
- So... also not quite what we want?


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Given a SAT formula $F$, graph $G=(V, E)$, we call algorithms that run in time $\mathcal{O}(|F|+|V|+|E|+\operatorname{enc}(S))$ instance-linear, where enc $(S):=\Sigma_{p \in S}|\operatorname{supp}(p)|$.

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## Symmetry Breaking: Refined Picture III



## Algorithms in the Paper

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Finest Disjoint Direct Decomposition: What it's about


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$$
\langle S\rangle=\operatorname{Aut}(G)
$$

$$
\begin{aligned}
& S=\{ \\
& \left(x_{1} x_{2} x_{3}\right)\left(\overline{x_{1} x_{2} x_{3}}\right)\left(y_{1} y_{2} y_{3}\right)\left(\overline{y_{1} y_{2} y_{3}}\right), \\
& \left(x_{1} x_{2}\right)\left(\overline{x_{1} x_{2}}\right)\left(y_{1} y_{2}\right)\left(\overline{y_{1} y_{2}}\right), \\
& \left.\left(z_{1} z_{2}\right)\left(\overline{z_{1} z_{2}}\right)\right\}
\end{aligned}
$$

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$$
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```
S={
(\mp@subsup{x}{1}{}\mp@subsup{x}{2}{}\mp@subsup{x}{3}{})(\overline{\mp@subsup{x}{1}{}\mp@subsup{x}{2}{}\mp@subsup{x}{3}{}})(\mp@subsup{y}{1}{}\mp@subsup{y}{2}{}\mp@subsup{y}{3}{})(\overline{\mp@subsup{y}{1}{}\mp@subsup{y}{2}{}\mp@subsup{y}{3}{}}),
(\mp@subsup{x}{1}{}\mp@subsup{x}{2}{})(\overline{\mp@subsup{x}{1}{}\mp@subsup{x}{2}{}})(\mp@subsup{y}{1}{}\mp@subsup{y}{2}{})(\overline{\mp@subsup{y}{1}{}\mp@subsup{y}{2}{}}),
(z1 z
x's and y's are independent of z's
```


## Finest Disjoint Direct Decomposition: What it's about



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$$
\begin{array}{ll}
S=\{ & S=\{ \\
\left(x_{1} x_{2} x_{3}\right)\left(\overline{x_{1} x_{2} x_{3}}\right)\left(y_{1} y_{2} y_{3}\right)\left(\overline{y_{1} y_{2} y_{3}}\right), & \left(x_{1} x_{2} x_{3}\right)\left(\overline{x_{1} x_{2} x_{3}}\right)\left(y_{1} y_{2} y_{3}\right)\left(\overline{y_{1} y_{2} y_{3}}\right), \\
\left(x_{1} x_{2}\right)\left(\overline{x_{1} x_{2}}\right)\left(y_{1} y_{2}\right)\left(\overline{y_{1} y_{2}}\right), & \left(x_{1} x_{2}\right)\left(\overline{x_{1} x_{2}}\right)\left(y_{1} y_{2}\right)\left(\overline{y_{1} y_{2}}\right)\left(z_{1} z_{2}\right)\left(\overline{z_{1} z}\right. \\
\left.\left(z_{1} z_{2}\right)\left(\overline{z_{1} z_{2}}\right)\right\} & \left.\left(z_{1} z_{2}\right)\left(\overline{z_{1} z_{2}}\right)\right\} \\
x^{\prime} s \text { and } y^{\prime} \text { s are independent of } z \text { 's } & \text { Here they are not? }
\end{array}
$$

## Finest Disjoint Direct Decomposition: Flip edges



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## Finest Disjoint Direct Decomposition: Algorithm

(1) color vertices with "orbits", connect vertices of orbit with a path


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## Lemma

Vertices are in the same connected component if and only if they are in the same factor of the finest direct disjoint decomposition.

## Finest Disjoint Direct Decomposition: Algorithm

- we can split generators according to connected components


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```
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\(\left(x_{1} x_{2}\right)\left(\overline{x_{1} x_{2}}\right)\left(y_{1} y_{2}\right)\left(\overline{y_{1} y_{2}}\right)\left(z_{1} z_{2}\right)\left(\overline{z_{1} z_{2}}\right)\),
\(\left.\left(z_{1} z_{2}\right)\left(\overline{z_{1} z_{2}}\right)\right\}\)
```

not independent

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- we can split generators according to connected components


$$
\begin{aligned}
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\end{aligned}
$$

not independent
$S=\{$
$\left(x_{1} x_{2} x_{3}\right)\left(\overline{x_{1} x_{2} x_{3}}\right)\left(y_{1} y_{2} y_{3}\right)\left(\overline{y_{1} y_{2} y_{3}}\right)$,
$\left(x_{1} x_{2}\right)\left(\overline{x_{1} x_{2}}\right)\left(y_{1} y_{2}\right)\left(\overline{y_{1} y_{2}}\right)$,
$\rightarrow \quad\left(z_{1} z_{2}\right)\left(\overline{z_{1} z_{2}}\right)$,
$\left.\left(z_{1} z_{2}\right)\left(\overline{z_{1} z_{2}}\right)\right\}$
independent

## Summary

Step 1:
detection
tep 2:
analysis

Step 3:
exploitation


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Step 1: detection


- make use of joint graph-group pairs to get fast, generic algorithms and heuristics


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Step 1: detection


- make use of joint graph-group pairs to get fast, generic algorithms and heuristics
- work to do to put this in practice (no 1:1 replacement for heuristics!)
- want to detect more involved group structures

